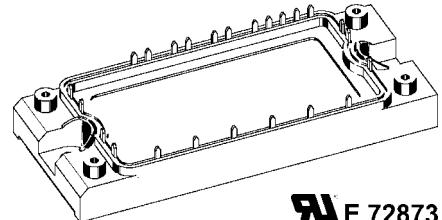
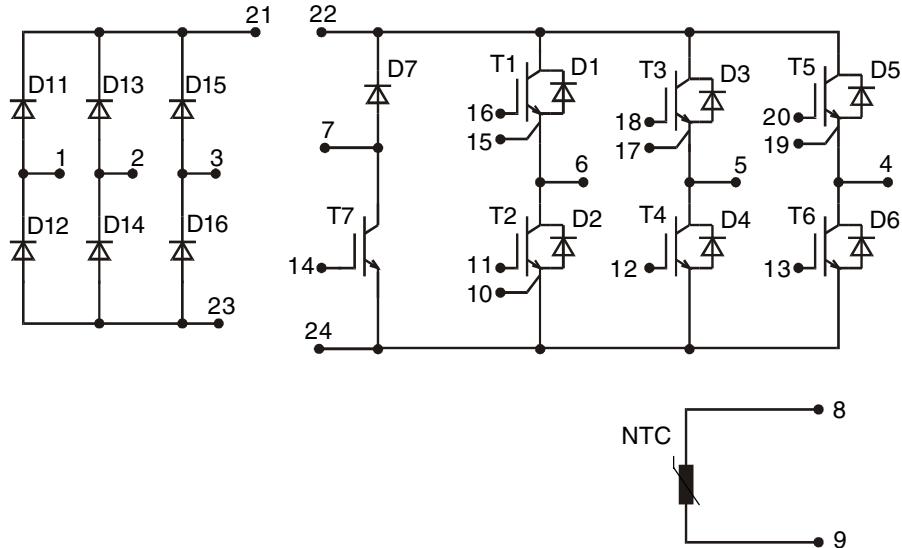


Converter - Brake - Inverter Module (CBI2)



E 72873

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600V$	$V_{CES} = 1200 V$	$V_{CES} = 1200 V$
$I_{DAVM} = 36 A$	$I_{C25} = 20 A$	$I_{C25} = 35 A$
$I_{FSM} = 300 A$	$V_{CE(sat)} = 2.3 V$	$V_{CE(sat)} = 2.1 V$

Input Rectifier Bridge D11 - D16

Symbol	Conditions	Maximum Ratings		
V_{RRM}		1600		V
I_{FAV}	$T_c = 80^\circ\text{C}$; sine 180°	25		A
I_{DAVM}	$T_c = 80^\circ\text{C}$; rectangular; $d = 1/3$	24		A
I_{FSM}	$T_{VJ} = 25^\circ\text{C}$; $t = 10 \text{ ms}$; sine 50 Hz	300		A
P_{tot}	$T_c = 25^\circ\text{C}$	100		W

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- Fast rectifier diodes for enhanced EMC behaviour
- NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Symbol	Conditions	Characteristic Values		
		($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)		
		min.	typ.	max.
V_F	$I_F = 15 A$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.3 1.3	1.6 V
I_R	$V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.2	0.15 mA mA
t_{rr}	$V_R = 100 V$; $I_F = 15 A$; $di/dt = -15 A/\mu\text{s}$		1	μs
R_{thJC}	(per diode)			1.3 K/W

Output Inverter T1 - T6

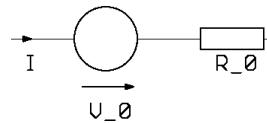
Symbol	Conditions	Maximum Ratings		
V_{CES}	$T_{VJ} = 25^\circ\text{C}$ to 150°C	1200		V
V_{GES}	Continuous	± 20		V
V_{GEM}	Transient	± 30		V
I_{C25}	$T_c = 25^\circ\text{C}$	35		A
I_{C80}	$T_c = 80^\circ\text{C}$	25		A
RBSOA	$V_{GE} = \pm 15 \text{ V}$; $R_G = 82 \Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 35$		A
t_{sc} (SCSOA)	$V_{CE} = V_{CES}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 82 \Omega$; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	$V_{CEK} \leq V_{CES}$	10	μs
P_{tot}	$T_c = 25^\circ\text{C}$	180		W

Symbol	Conditions	Characteristic Values		
		($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)	min.	typ.
$V_{CE(sat)}$	$I_C = 15 \text{ A}$; $V_{GE} = 15 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2.1	2.6
			2.3	V
$V_{GE(th)}$	$I_C = 0.6 \text{ mA}$; $V_{GE} = V_{CE}$	4.5		6.5
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.9	mA
I_{GES}	$V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$		200	nA
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	$\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^\circ\text{C} \\ V_{CE} = 600 \text{ V}; I_C = 15 \text{ A} \\ V_{GE} = \pm 15 \text{ V}; R_G = 82 \Omega \end{array} \right\}$	100		ns
		70		ns
		500		ns
		70		ns
		2.3		mJ
		1.8		mJ
C_{ies}	$V_{CE} = 25 \text{ V}$; $V_{GE} = 0 \text{ V}$; $f = 1 \text{ MHz}$	1000		pF
Q_{Gon}	$V_{CE} = 600 \text{ V}$; $V_{GE} = 15 \text{ V}$; $I_C = 15 \text{ A}$	70		nC
R_{thJC}	(per IGBT)		0.7	K/W

Output Inverter D1 - D6

Symbol	Conditions	Maximum Ratings		
I_{F25}	$T_c = 25^\circ\text{C}$	28		A
I_{F80}	$T_c = 80^\circ\text{C}$	18		A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
V_F	$I_F = 15 \text{ A}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2.7	V
		1.8		V
t_{rr} I_{RM}	$\left. \begin{array}{l} I_F = 15 \text{ A}; di_F/dt = -400 \text{ A}/\mu\text{s} \\ V_R = 600 \text{ V}; V_{GE} = 0 \text{ V} \end{array} \right\}$	16		A
		130		ns
R_{thJC}	(per diode)		2.1	K/W

Equivalent Circuits for Simulation**Conduction****D11 - D16**

Rectifier Diode (typ. at $T_J = 125^\circ\text{C}$)
 $V_o = 1.08 \text{ V}$; $R_o = 15 \text{ m}\Omega$

T1 - T6 / D1 - D6

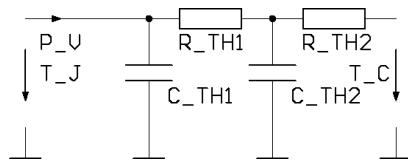
IGBT (typ. at $V_{GE} = 15 \text{ V}$; $T_J = 125^\circ\text{C}$)
 $V_o = 1.37 \text{ V}$; $R_o = 62 \text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^\circ\text{C}$)
 $V_o = 1.32 \text{ V}$; $R_o = 30 \text{ m}\Omega$

T7 / D7

IGBT (typ. at $V_{GE} = 15 \text{ V}$; $T_J = 125^\circ\text{C}$)
 $V_o = 1.32 \text{ V}$; $R_o = 131 \text{ m}\Omega$

Free Wheeling Diode (typ. at $T_J = 125^\circ\text{C}$)
 $V_o = 1.39 \text{ V}$; $R_o = 56 \text{ m}\Omega$

Thermal Response**D11 - D16**

Rectifier Diode (typ.)
 $C_{th1} = 0.106 \text{ J/K}$; $R_{th1} = 1.06 \text{ K/W}$
 $C_{th2} = 0.79 \text{ J/K}$; $R_{th2} = 0.239 \text{ K/W}$

T1 - T6 / D1 - D6

IGBT (typ.)
 $C_{th1} = 0.156 \text{ J/K}$; $R_{th1} = 0.545 \text{ K/W}$
 $C_{th2} = 1.162 \text{ J/K}$; $R_{th2} = 0.155 \text{ K/W}$

Free Wheeling Diode (typ.)

$C_{th1} = 0.065 \text{ J/K}$; $R_{th1} = 1.758 \text{ K/W}$
 $C_{th2} = 0.639 \text{ J/K}$; $R_{th2} = 0.342 \text{ K/W}$

T7 / D7

IGBT (typ.)
 $C_{th1} = 0.09 \text{ J/K}$; $R_{th1} = 0.954 \text{ K/W}$
 $C_{th2} = 0.809 \text{ J/K}$; $R_{th2} = 0.246 \text{ K/W}$

Free Wheeling Diode (typ.)

$C_{th1} = 0.043 \text{ J/K}$; $R_{th1} = 2.738 \text{ K/W}$
 $C_{th2} = 0.54 \text{ J/K}$; $R_{th2} = 0.462 \text{ K/W}$

Brake Chopper T7

Symbol	Conditions	Maximum Ratings		
V_{CES}	$T_{VJ} = 25^\circ\text{C}$ to 150°C	1200		V
V_{GES}	Continuous	± 20		V
V_{GEM}	Transient	± 30		V
I_{C25}	$T_C = 25^\circ\text{C}$	20		A
I_{C80}	$T_C = 80^\circ\text{C}$	15		A
RBSOA	$V_{GE} = \pm 15 \text{ V}$; $R_G = 82 \Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 20$ $V_{CEK} \leq V_{CES}$		A
t_{sc} (SCSOA)	$V_{CE} = 720 \text{ V}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 82 \Omega$; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10		μs
P_{tot}	$T_C = 25^\circ\text{C}$	105		W

Symbol	Conditions	Characteristic Values		
		($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 10 \text{ A}$; $V_{GE} = 15 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.3 2.7	2.7	V
$V_{GE(th)}$	$I_C = 0.4 \text{ mA}$; $V_{GE} = V_{CE}$	4.5		V
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.3	0.5	mA
I_{GES}	$V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$		200	nA
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}$; $I_C = 10 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$; $R_G = 82 \Omega$	50 40 290 60 1.2 1.1		ns ns ns ns mJ mJ
C_{ies} Q_{Gon}	$V_{CE} = 25 \text{ V}$; $V_{GE} = 0 \text{ V}$; $f = 1 \text{ MHz}$ $V_{CE} = 600 \text{ V}$; $V_{GE} = 15 \text{ V}$; $I_C = 10 \text{ A}$	600 45		pF nC
R_{thJC}			1.2	K/W

Brake Chopper D7

Symbol	Conditions	Maximum Ratings		
V_{RRM}	$T_{VJ} = 25^\circ\text{C}$ to 150°C	1200		V
I_{F25}	$T_C = 25^\circ\text{C}$	17		A
I_{F80}	$T_C = 80^\circ\text{C}$	11		A
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
V_F	$I_F = 10 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.9	2.9	V
I_R	$V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.07	0.06	mA
I_{RM} t_{rr}	$I_F = 10 \text{ A}$; $di_F/dt = -400 \text{ A}/\mu\text{s}$; $T_{VJ} = 125^\circ\text{C}$ $V_R = 600 \text{ V}$	13 110		A ns
R_{thJC}			3.2	K/W

Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
R_{25} $B_{25/50}$	$T = 25^\circ\text{C}$	4.75	5.0 3375	5.25 k Ω K

Module

Symbol	Conditions	Maximum Ratings		
T_{VJ}	Operating	-40...+125	$^\circ\text{C}$	
T_{JM}		150	$^\circ\text{C}$	
T_{stg}		-40...+125	$^\circ\text{C}$	
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~	
M_d	Mounting torque (M5)	2.7 - 3.3	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m Ω
d_s	Creepage distance on surface	6		mm
d_A	Strike distance in air	6		mm
R_{thCH}	with heatsink compound	0.02		K/W
Weight		180		g

Dimensions in mm (1 mm = 0.0394")

